

METROPOLITAN STATE UNIVERSITY OF DENVER Office of Academic and Student Affairs

REGULAR COURSE SYLLABUS

College of: Professional Stu	<u>udies</u>				
Department: Engineering	and Engineering Te	echnology			
Prefix & Course Number:	: <u>CPE 4710</u>	Crosslisted V	Vith*:		
Course Title: Digital Cont	trol System Design				
Transcript Course Title (3	30 characters): <u>Dig</u>	ital Control Sys	tem Design		
Check All That Apply:	Required for Major: Required for Minor: Specified Elective: X				
	Required for Conc	entration:	_ Elective:	Service Course:	
hour. The Higher Learning Co with this definition. Federal Credit Ho outcomes and verit equivalency that re (1) one hour of clas work each week for twelve weeks for on time; or (2) at least activities as establis other academic wo	ommission requires instant of the commission requires instant of the commission requires instant of the commission of th	edit hour is an arestudent achiever attes not less that ulty instruction are meeks for on redit, or the equipant of work as reson, including laborthe award of contact of the award of contact and t	tain policies and mount of work ment that is and in: and a minimund e semester of ivalent amound equired in para oratory work, and it hours. 34	ply with the federal definition of a credit d procedures for verifying compliance represented in intended learning in institutionally-established on of two hours of out-of-class student retrimester hour of credit, or ten to be a to federal to	
Face-to-Face or Equi					
			Other (please s	pecify type and hours):	
Additional Student W	Vork Hours per cou	ırse: <u>120</u>			
Variable topics umbrella	course: No X Ye	es If yes	, number of co	redits/repeats allowed	
Specified repeatable cour	rse: No X Yes	If yes, num	ber of credits/	repeats allowed	
Prerequisite(s): CPE 3715	5 (with a grade of "C	C" or better for a	all prerequisite	<u>es)</u>	
Corequisite(s):					
Prerequisite(s) or Corequ	aisite(s):				
APPROVED:					
Department Chair OR Prog	gram Director			Date	
Dean OR Associate Dean				Date	
Associate VP, Academic and Student Affairs				Date	

*If crosslisted, attach completed Course Crosslisting Agreement Form

Prefix and Course Number:

(76)

Banner	Enforced	Coding:
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Prerequisite(s): <u>CPE 3715</u> (with a grade of "C" or better for all prerequisites)

Corequisite(s): _____

Prerequisite(s) or Corequisite(s): _____

Registration restrictions: Level _____ Class _____Program/Major ____ Student attribute ____

Catalog Course Description:

Students in this course will learn the process and theory of the design of digital control systems, using classical and modern control theory. State variable feedback control and other optimal control theories will be covered.

Specific Variable Topics Course Description (if applicable, umbrella course description included above):

Required Reading and Other Materials will be equivalent to:

Phillips (2014). Digital Control System Analysis & Design, 4th edition or latest edition. Upper Saddle Hill, NJ: Prentice Hall.

Specific, Measurable Student Behavioral Learning Objectives:

Upon completion of this course the student should be able to:

- 1. Analyze both classical and modern digital control systems
 - a. Develop competency in the use of the z-transform as an analysis tool
 - b. Determine stability of systems through a wide variety of techniques
- 2. Develop methods for stable design of digital control systems
 - a. Use a variety of discrete mathematical techniques for digital control system design
 - b. Develop an understanding of the applications of digital control systems
- 3. Design a variety of digital control systems
 - a. Pole-placement technique
 - b. State variable feedback control systems
 - c. State observers control systems
 - d. Fuzzy logic control systems.

Detailed Outline of Course Content (Major Topics and Subtopics) or Outline of Field Experience/Internship (experience, responsibilities and supervision):

- I. Introduction to Digital Control
- II. Z-Transform
 - A. Discrete-time Systems
 - B. Transform Methods
 - C. Theorems of Z-transform
 - D. Solution of Difference Equations
 - E. Inverse Z-transform
- III. Sampling
 - A. Ideal Sampler
 - B. Practical Sampler
 - C. Sampled Control Systems
 - D. Data Reconstruction
 - E. A/D and D/A (brief)
 - F. Alias Filter Design

- IV. Time Response
 - A. System Time Response
 - B. Characteristic Equation
 - C. Analog s-plane/Digital z-plane Mapping
 - D. Steady-State Accuracy
- V. Stability Analysis
 - A. Introduction
 - B. Bilinear Transformation
- VI. Frequency Response
- VII. Robustness
- VIII. State Variable Model
 - A. Pole Placement Design
 - B. State Estimation
 - C. Observer Design
 - 1.Full-Order
 - 2. Reduced-Order
 - D. Controllability and Observability
 - E. Integral State Feedback
 - IX. Optimal Control (brief)
 - X. Fuzzy Logic
 - A. Concepts
 - B. Design

Evaluation of Student Performance:

- 1. Examinations
- 2. Written Assignments